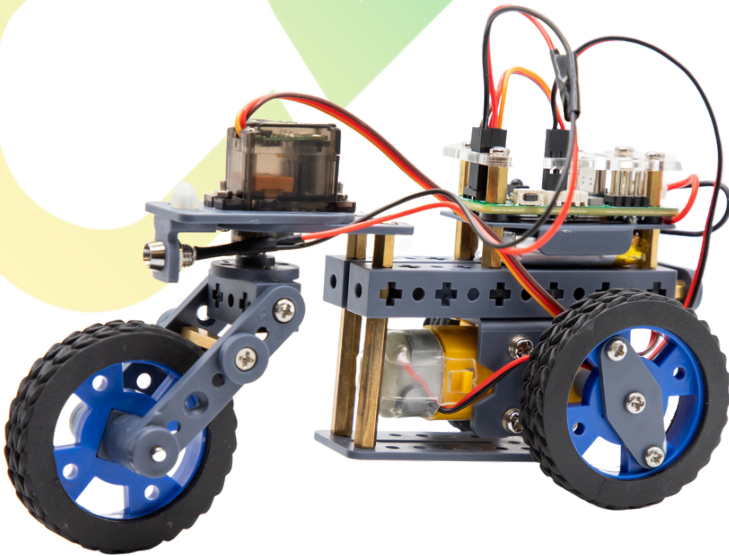
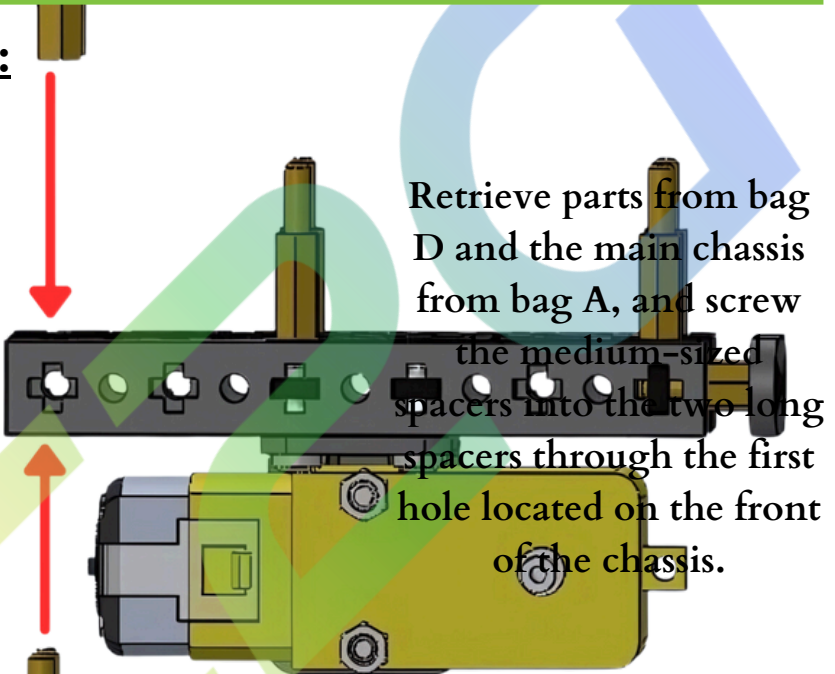
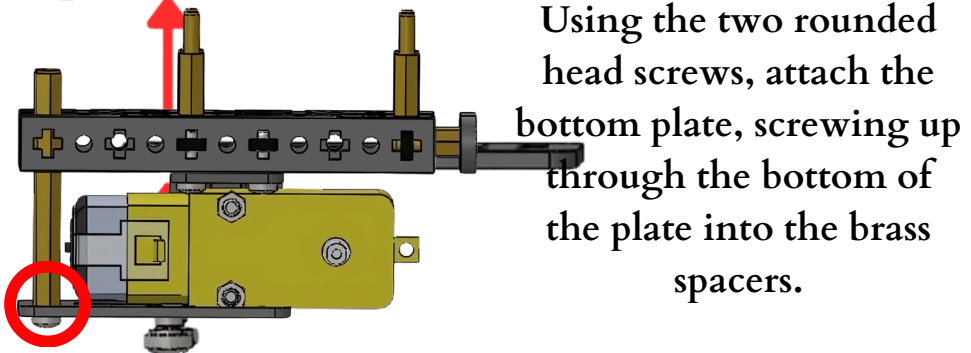
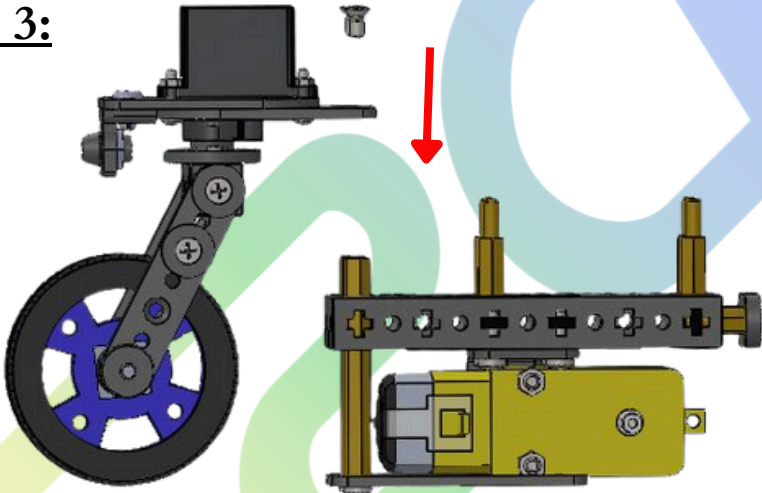


Student Instruction Manual

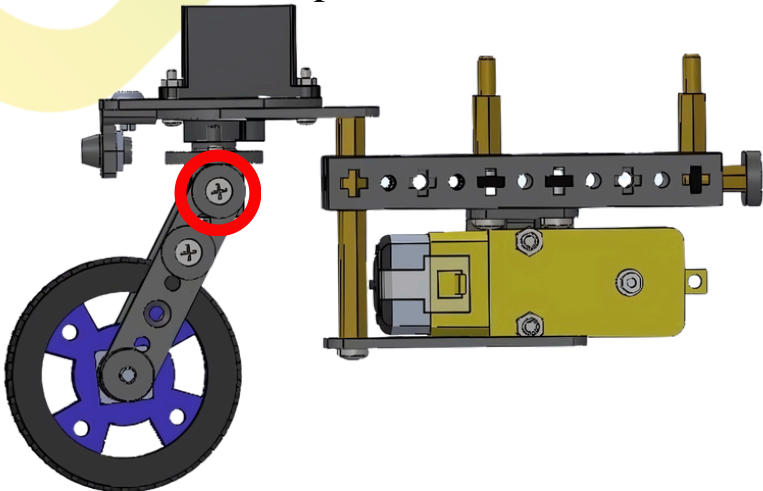
Motomo



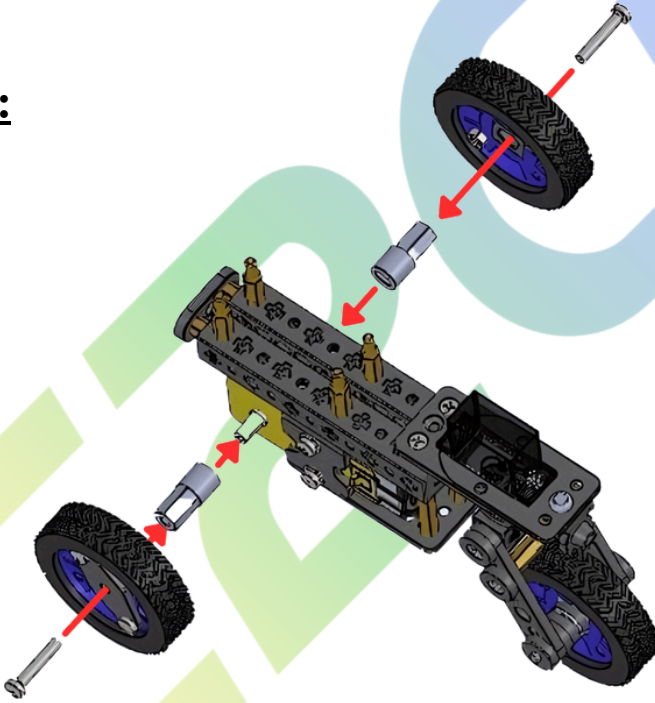
Step 1:Step 2:

Step 3:

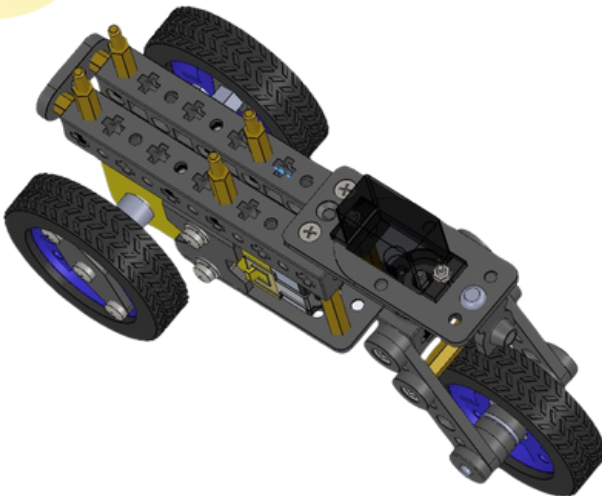
Find the front of the bike and two counter-sunk screws contained in bag B, screw them down through the top plate into the medium-sized spacers.



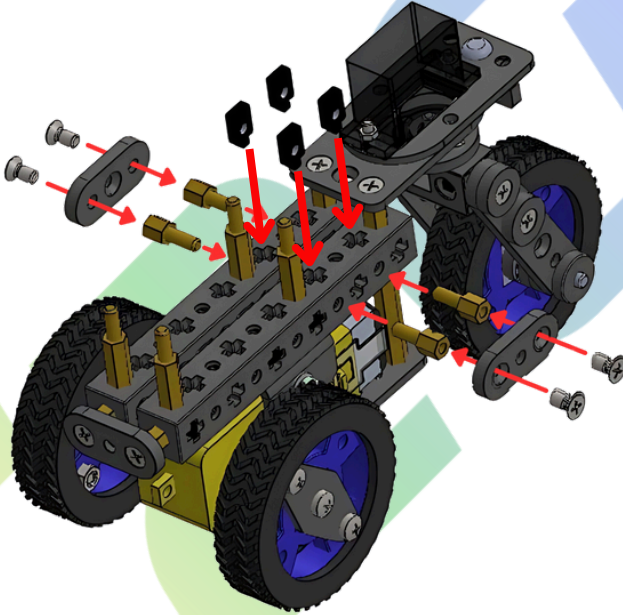
Ensure the headlight is facing forward. The front tire angle is adjustable at the indicated screw.

Step 4:

Attach the rear wheel using parts in bag E, and using the long screw secure the wheel onto the axle extenders.

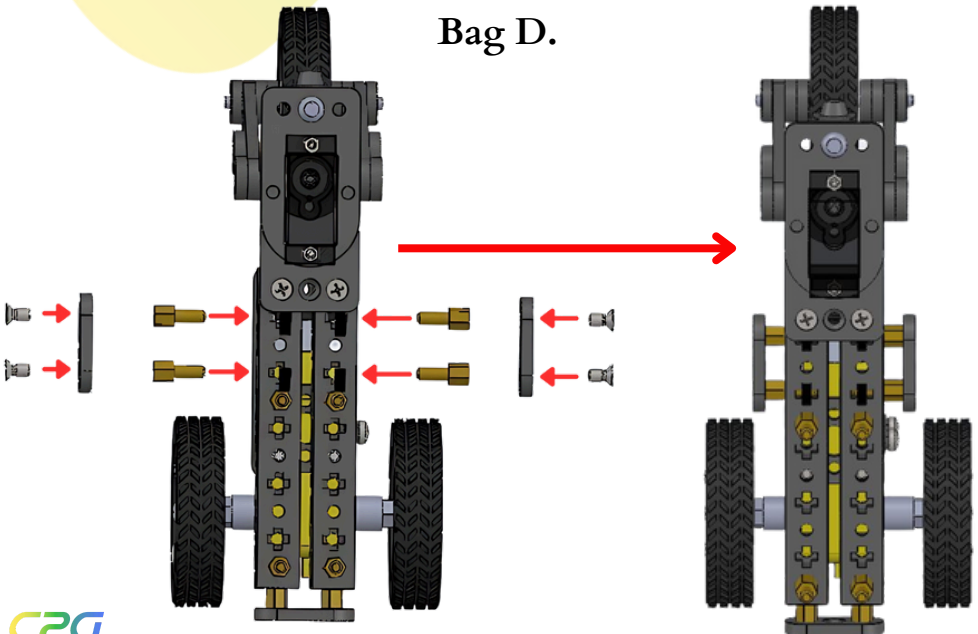


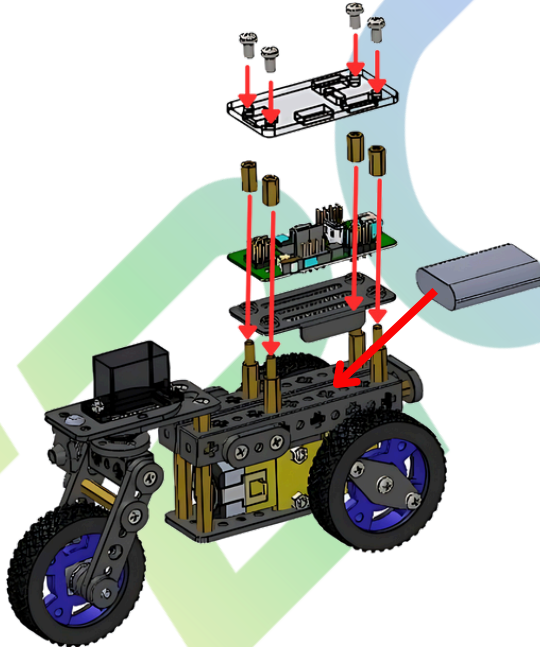
Step 5:



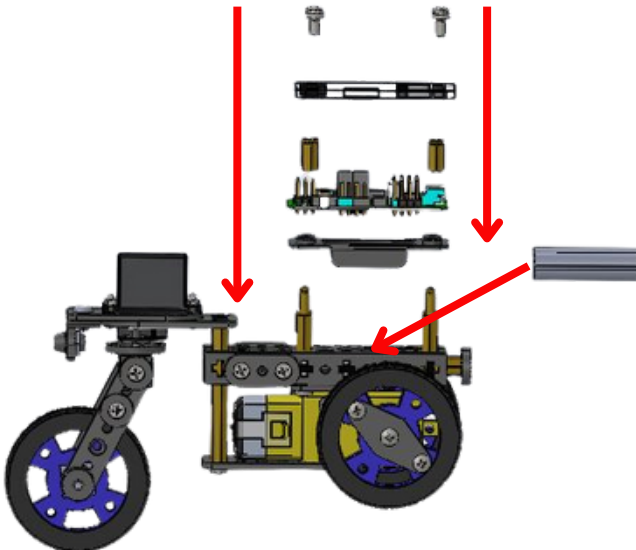
Place 4 black spacers into the top of the chassis blocks vertically, then insert 4 brass spacers tow on each side of the chassis, and secure the plastic footholds with two counter-sunk screws on each side all found in

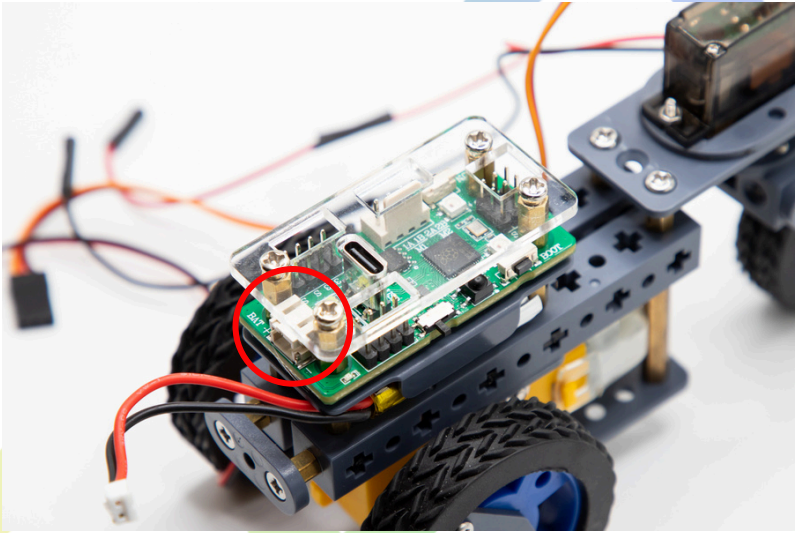
Bag D.



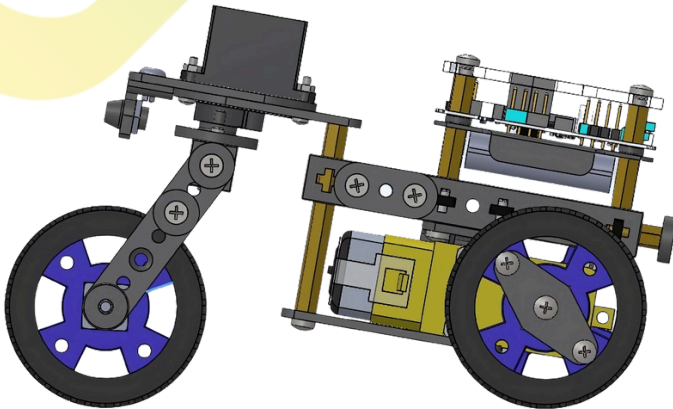
Step 6:

Attach the C2G Mini Microcontroller with the materials found in the C2G Mini box, first placing the battery in between the chassis upper spacers, then the battery divider followed by the C2G Mini, small brass spacers, peeled acrylic board, and 4 screws to secure.





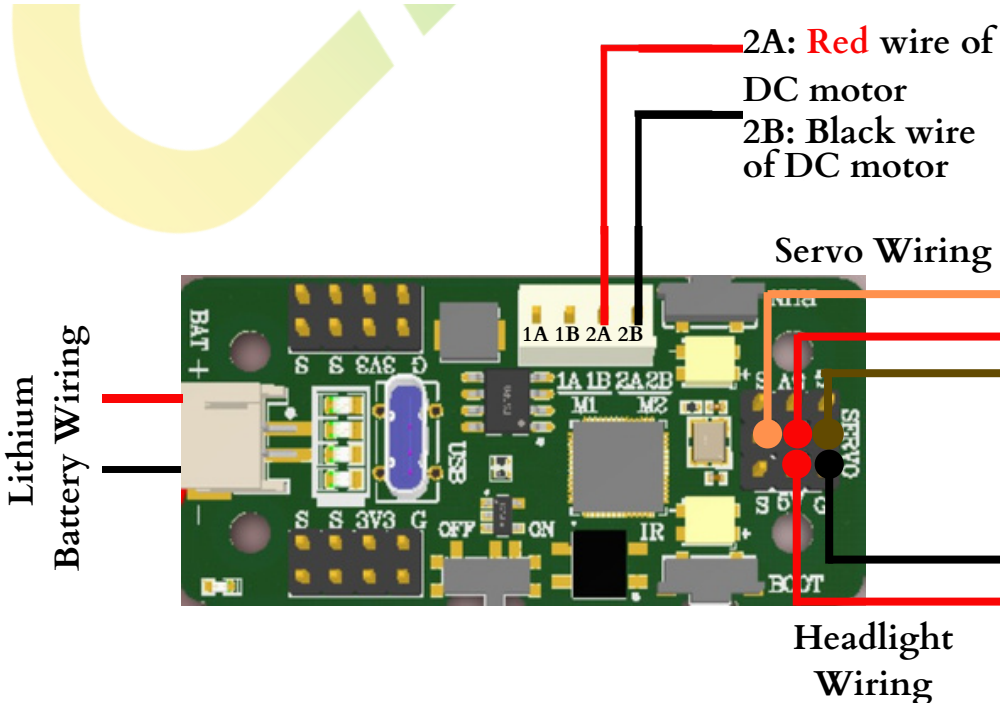
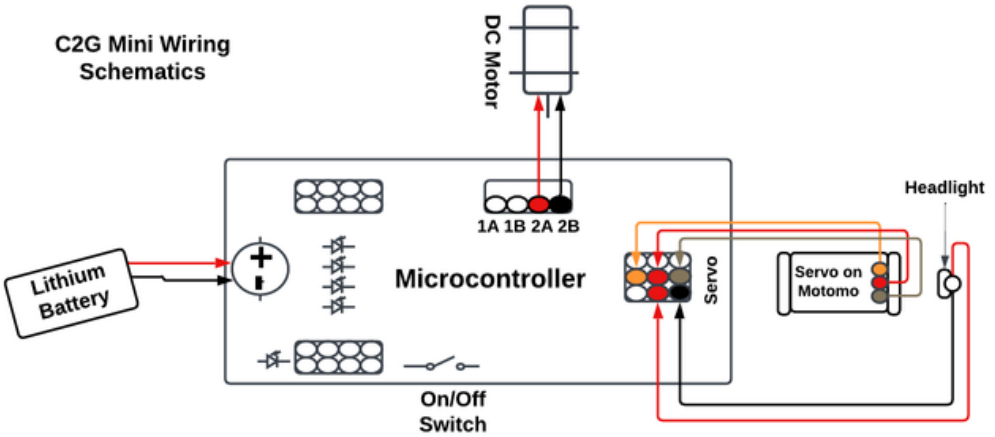
Ensure the battery pack wire and power port on the microcontroller are both facing the back of Motomo to allow for plug-in ease.



All hardware is assembled final steps include wiring of all electronic components.

How to wire the robot?

C2G Mini Wiring Schematics



**Congratulations on
completing the
Motomo build!**

